



**SWARM
2017**

Finalist

Best Student Paper Award

The 2nd International Symposium on Swarm
Behavior and Bioinspired Robotics

Evolutionary Acquisition of Congestion Management
of a Robotic Swarm in a Path Formation Task

Motoaki Hiraga, Toshiyuki Yasuda and Kazuhiro Ohkura

The 2nd International Symposium on Swarm
Behavior and Bioinspired Robotics
Kyoto, Japan,
October 31, 2017



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